

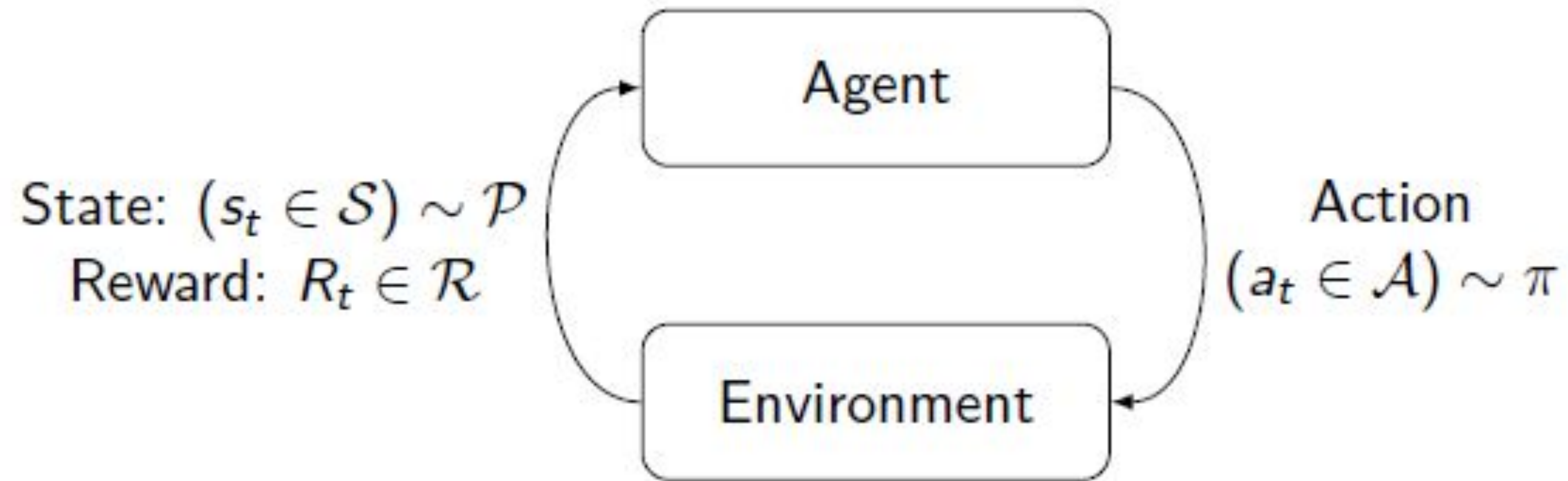
Reinforcement Learning & PyCIGAR Architecture

- **Reinforcement Learning:**
 - Branch of Artificial Intelligence which has demonstrated the ability to find optimal control policies in systems with complex dynamical interactions via intelligent simulation (i.e., “smart” trial and error)
- **PyCIGAR:**
 - Python-based simulation framework used for training and evaluation of RL agents
 - Brings together:
 - Dynamic models of smart inverter functions (based on IEEE 1547)
 - Distribution system power flow tools (OpenDSS & custom solvers)
 - Open source reinforcement learning library (RLlib: <https://docs.ray.io/en/master/rllib.html>)

Markov Decision Processes (MDPs)

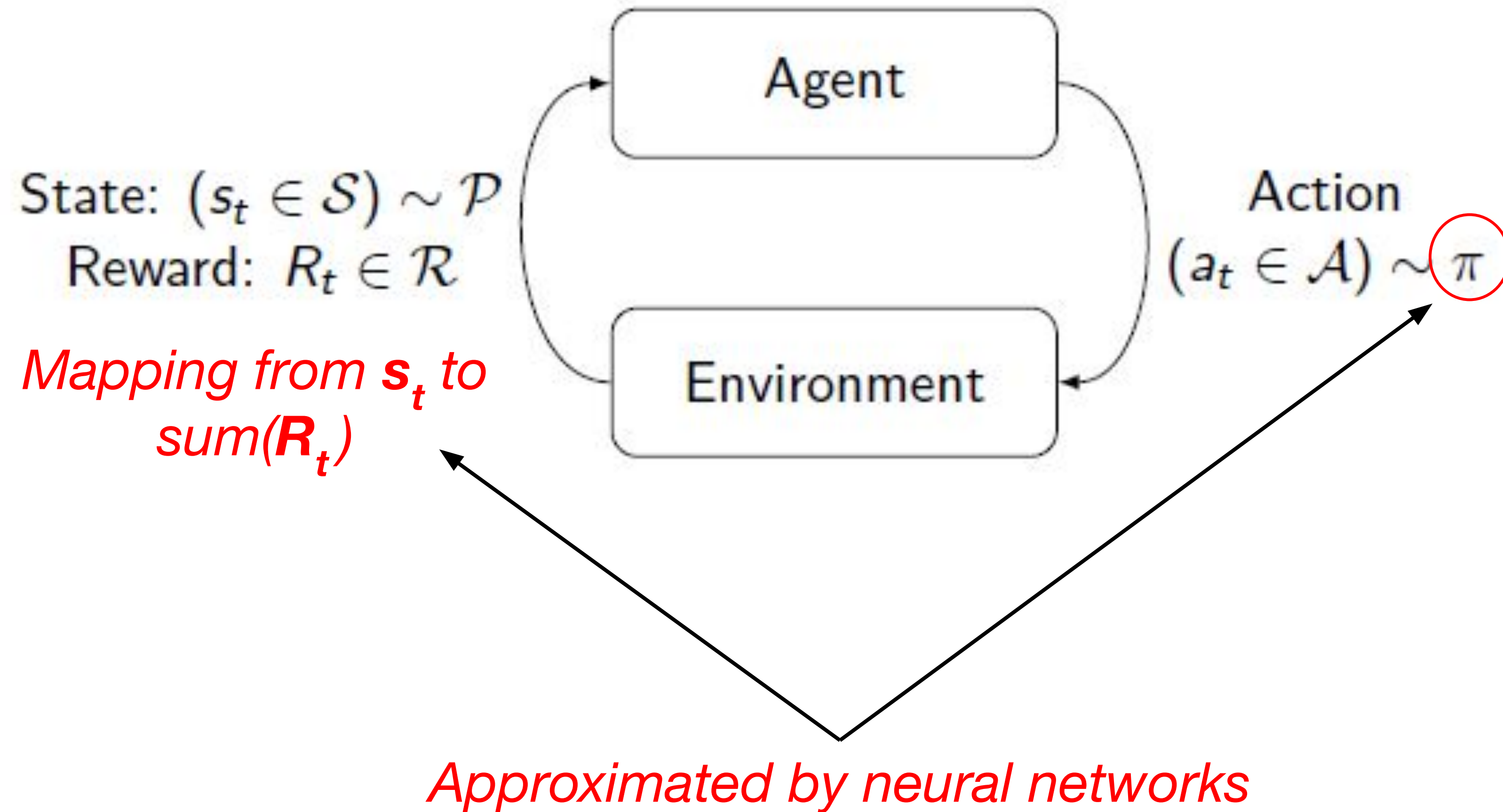
- *MDPs* provides a mathematical framework for modeling decision making in situations where outcomes are partly random and partly under the control of a decision maker.
- Consists of the 4-tuple: (S, A, P_a, R_a)
- **S** is the set of possible states (i.e., the *state space*)
- **A** is the set of admissible actions
- P_a is the probability that action **a** in state **s** at time **t** will lead to **s'** at **t+1**, or
$$P_a(s, s') = \mathcal{Pr}(s_{t+1} = s' | s_t = s, a_t = a)$$
- $R_a(\mathbf{s}, \mathbf{s}')$ is the reward received after applying **a** at state **s** to transition to **s'**
- Goal of the optimization is to maximize the cumulative reward over a time horizon
- Can also be solved by dynamic programming or Monte Carlo techniques

Reinforcement Learning Agent Training

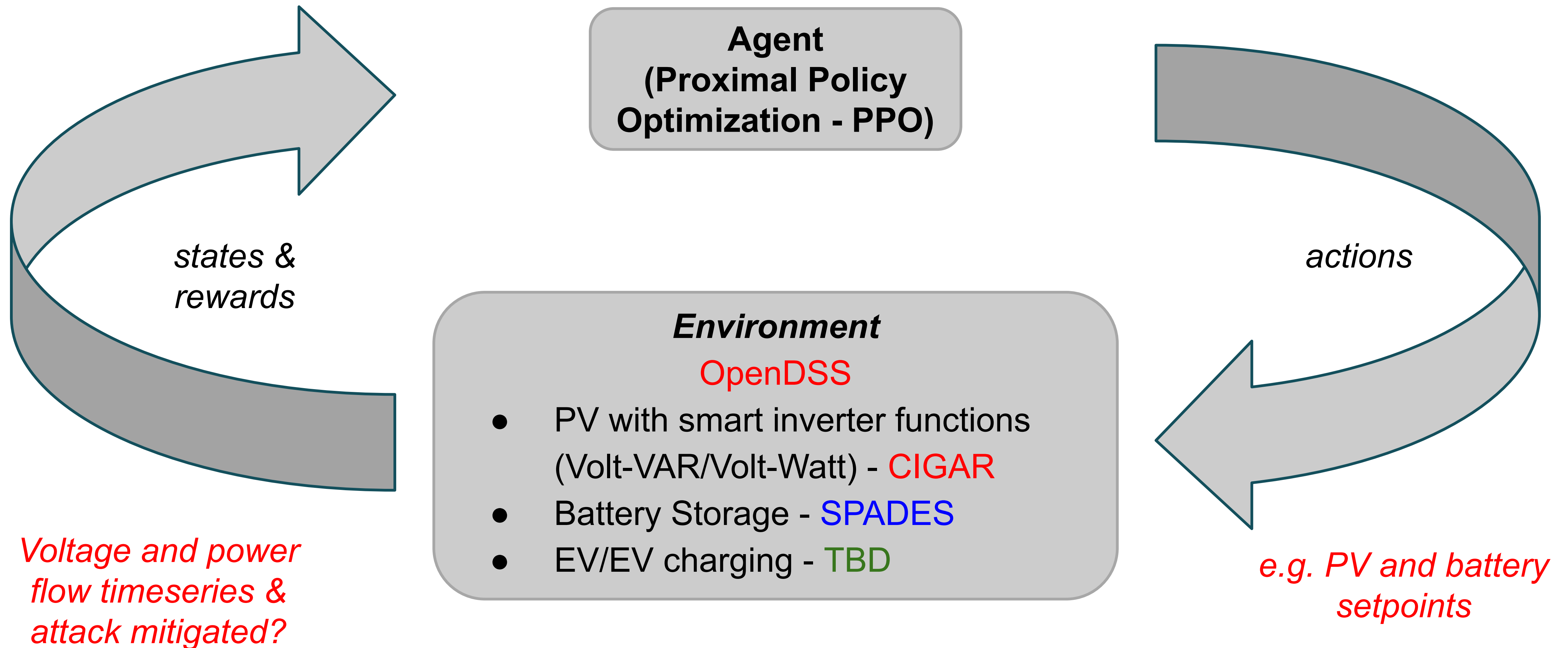


- At time t the agent selects action \mathbf{a}_t from a policy $\boldsymbol{\pi}$ and applies that action to the environment
- Action causes a transition to a new state \mathbf{s}_t which has an associated reward \mathbf{R}_t
- $(\mathbf{s}_t, \mathbf{a}_t, \mathbf{R}_t)$ are used to update the policy $\boldsymbol{\pi}$

Reinforcement Learning Agent Training

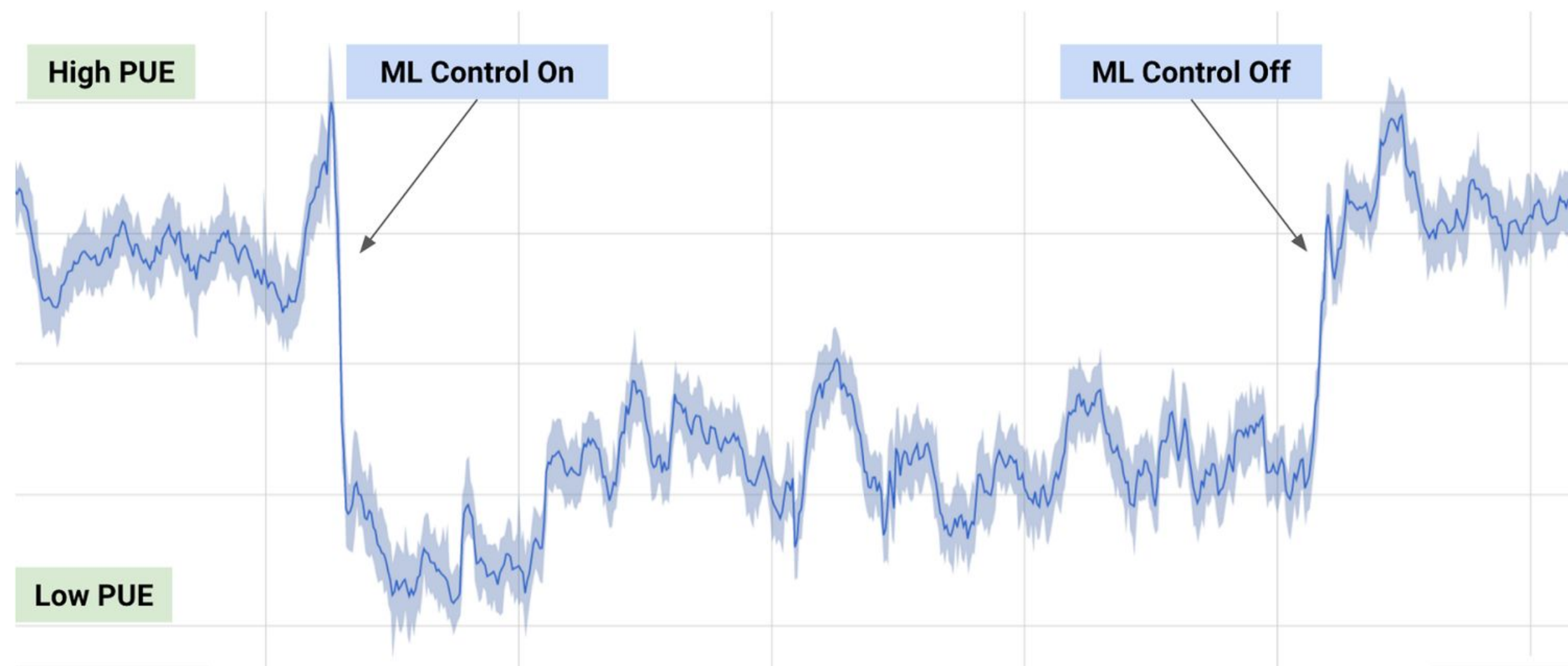


Reinforcement Learning Training Loop

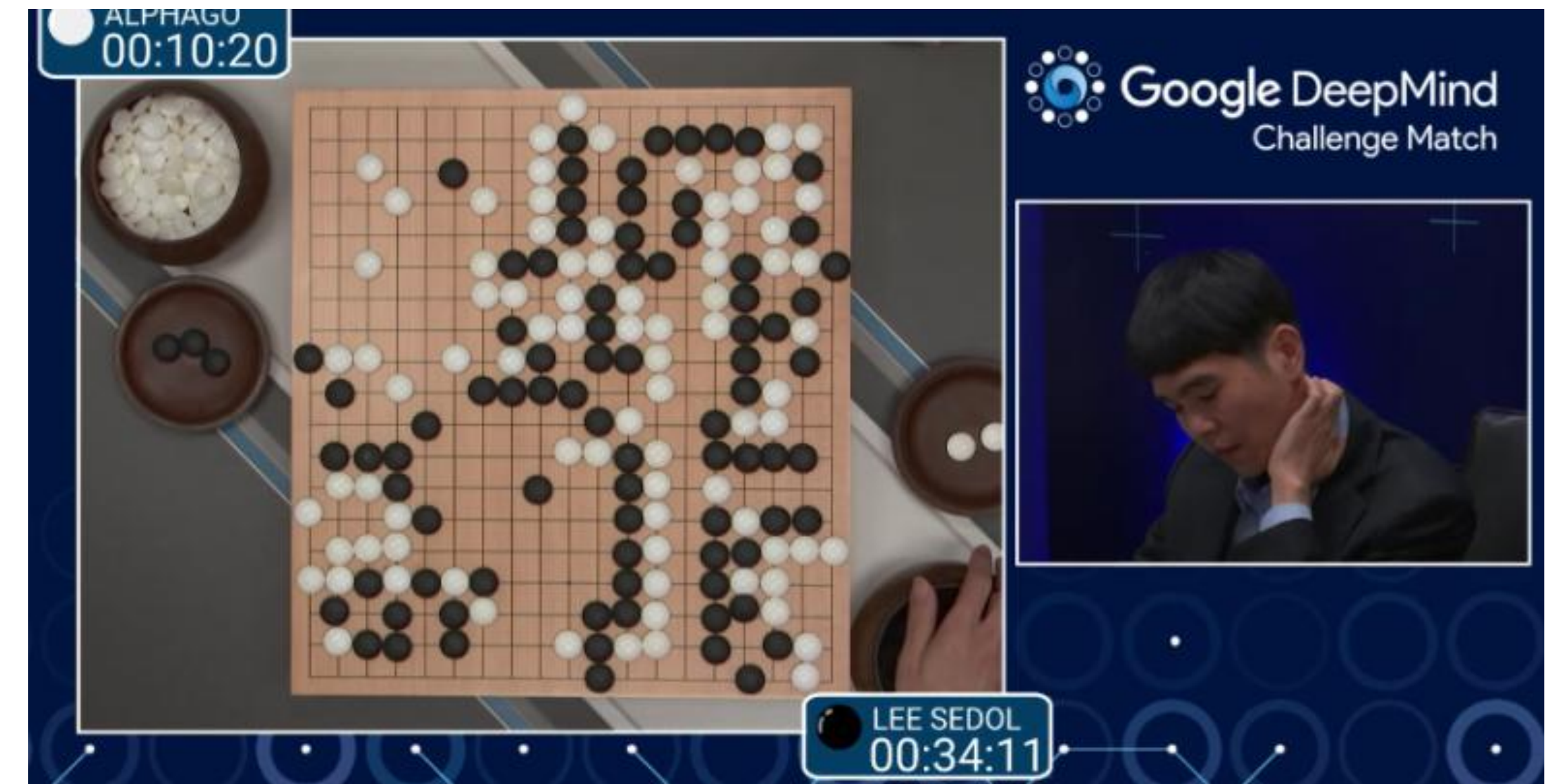


Examples of Reinforcement Learning

Machine Learning Improves Google Data Center Cooling Efficiency



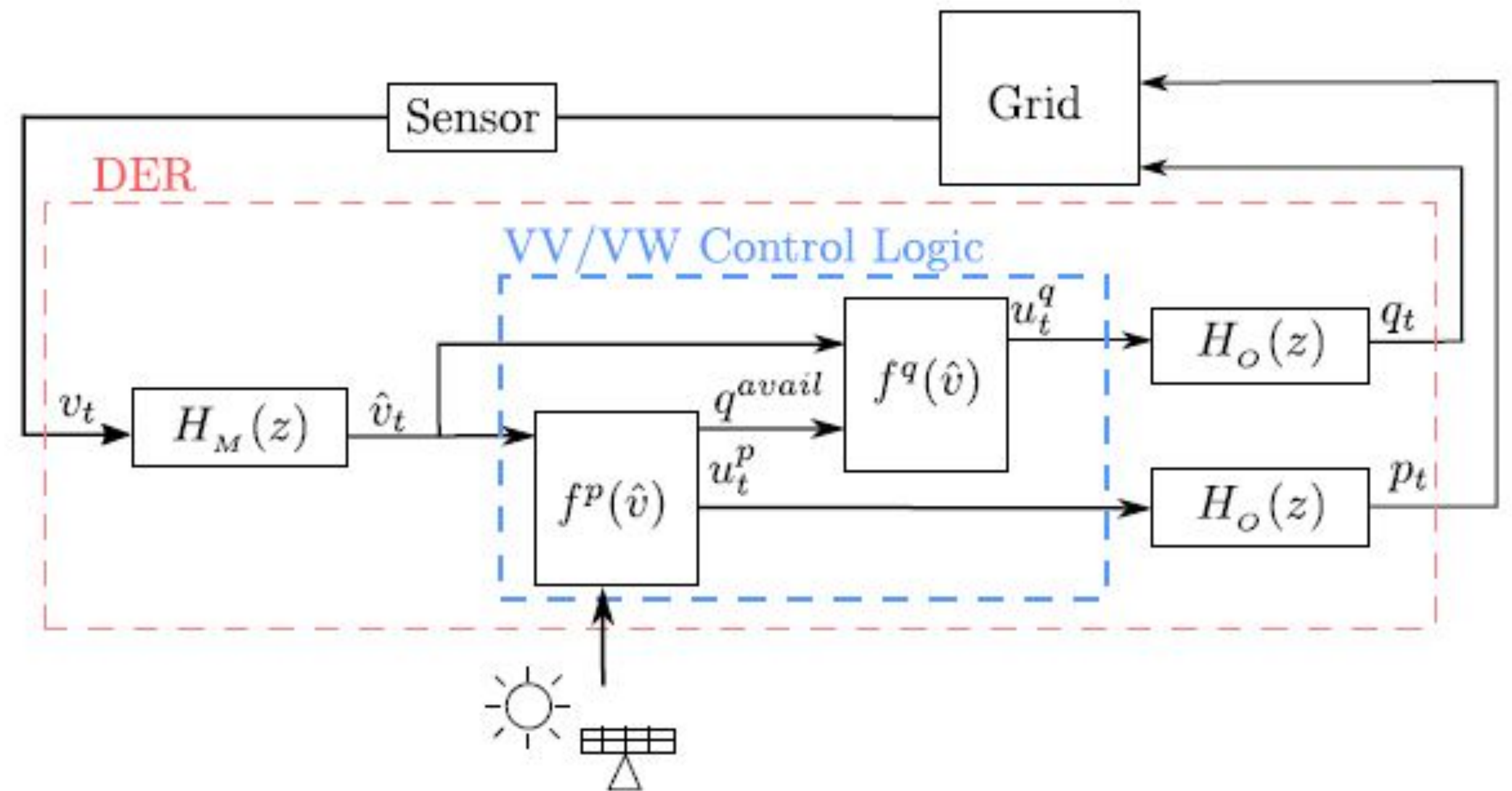
Reinforcement Learning Beats “Go” Expert



These algorithms enable decision-making in high dimensional uncertain problems

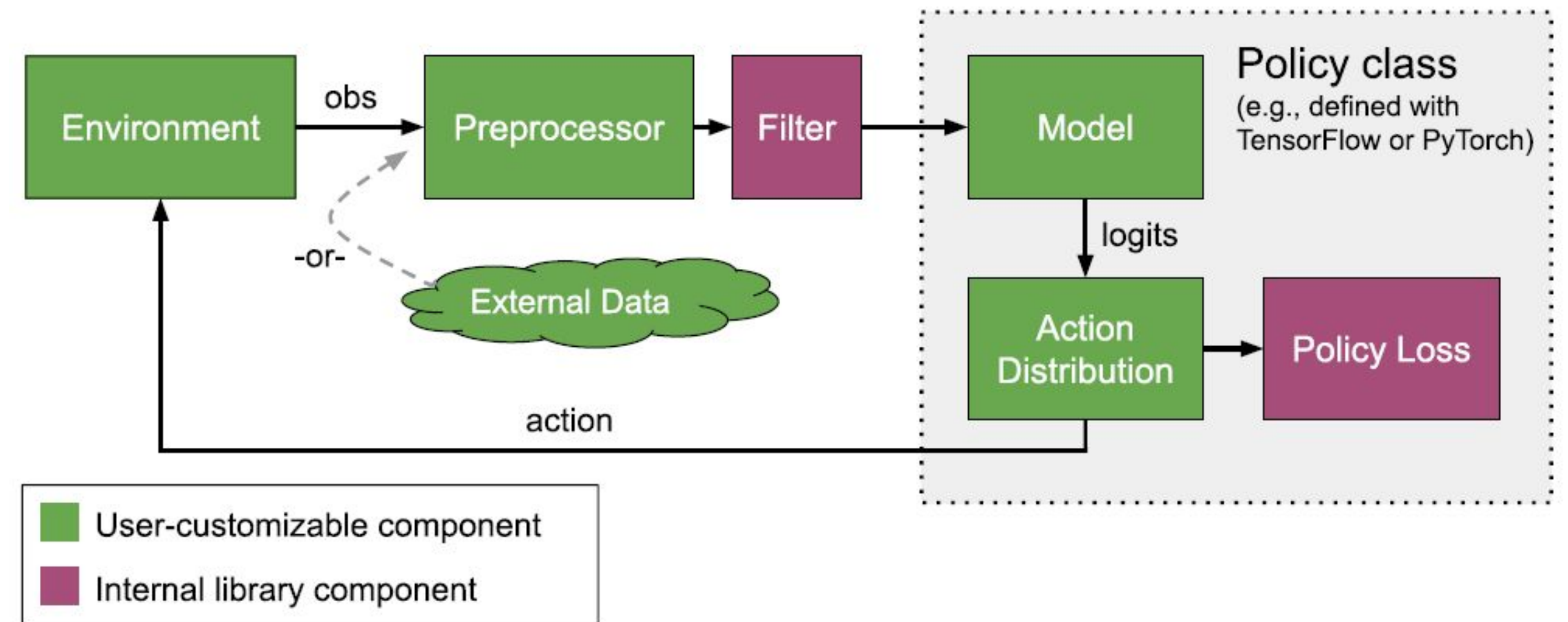
PyCIGAR - Smart Inverter Models

- PyCIGAR smart inverter module replicates the dynamic behavior of the Volt-VAR and Volt-Watt control
- $H_M(z), H_O(z)$ are low pass filters
- $f^q(\hat{v})$: inverter Volt-VAR curve
- $f^p(\hat{v})$: inverter Volt-Watt curve
- Volt-Watt precedence: available reactive power determined by excess inverter capacity

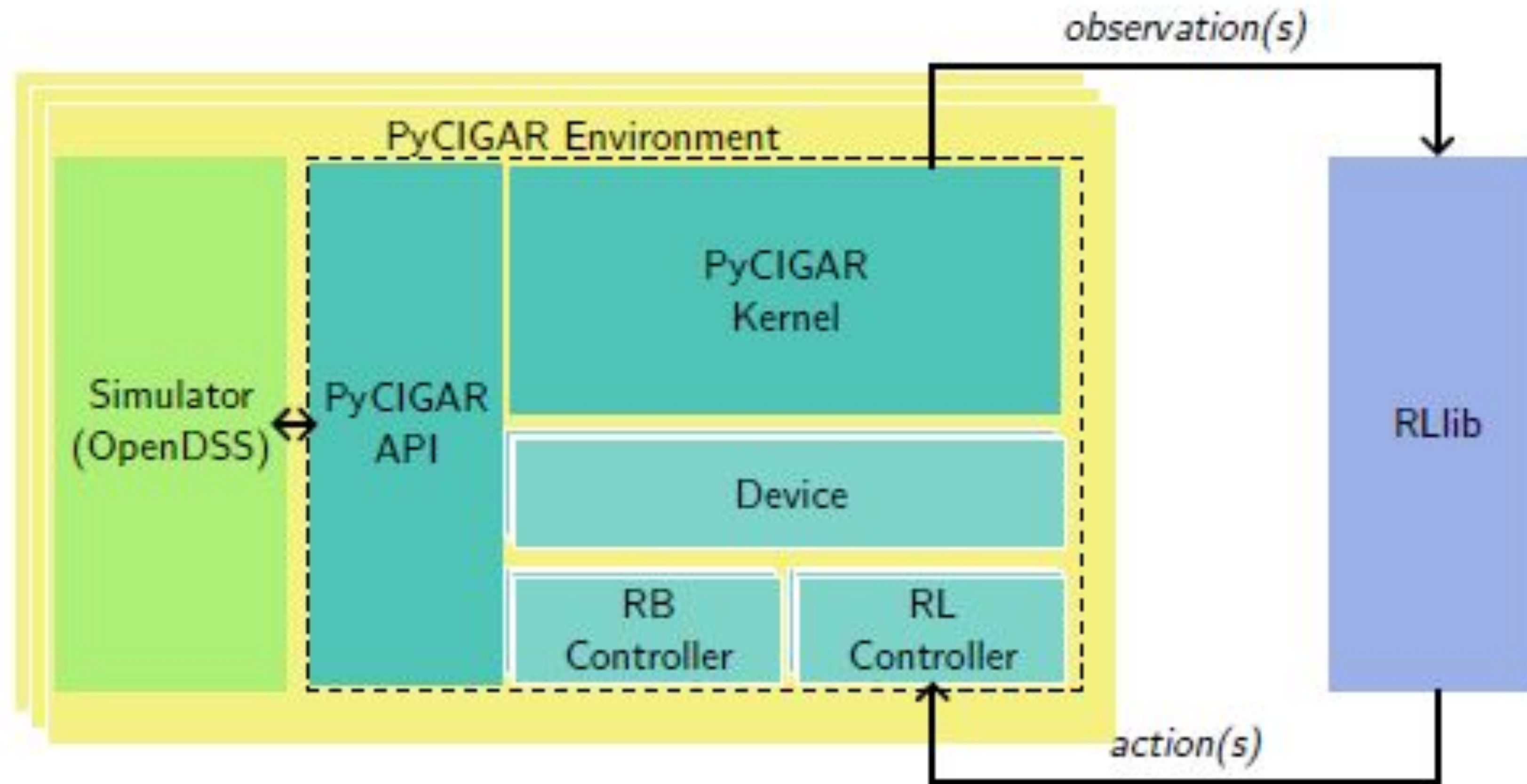


PyCIGAR - RLlib/Ray

- RLlib is a scalable open-source library for reinforcement learning
- Provides application support
 - Multi-agent/hierarchical
- Abstractions of multiple RL algorithms:
 - PPO, DDPG, A3C, etc.
- Supports distributed training
- Highly customizable



PyCIGAR Environment



*RB Controller: Rule-based controller

*RL Controller: Reinforcement learning controller

Questions/Discussion
